

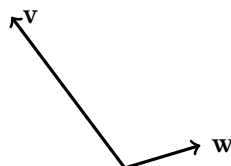
## Homework 5

DUE: TUESDAY, FEBRUARY 25

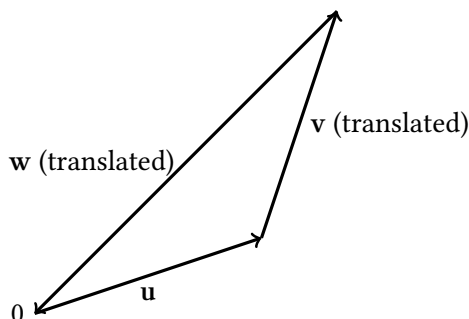
**This week.** Read through 4.9. Intuitively understand the difference between a vector and its coordinate vector with respect to some basis.

## Bases and Coordinate Vectors

1. In the accompanying figure, sketch the vector  $\mathbf{u}$  with  $[\mathbf{u}]_{\mathcal{B}} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$ , where  $\mathcal{B}$  is the basis for  $\mathbb{R}^2$  consisting of the vectors  $\mathbf{v}$ ,  $\mathbf{w}$ .



2. Consider the vectors  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  sketched in the accompanying figure. Find the coordinate vector of  $\mathbf{w}$  with respect to the basis  $\mathbf{u}$ ,  $\mathbf{v}$ .



3. Let  $\mathcal{B} = \{e_1, e_2, e_3, e_4\}$  be the standard ordered basis for  $\mathbb{R}^4$  and let  $\mathcal{C} = \{e_3, e_1, e_2, e_4\}$ . Compute the change of bases matrices  $P_{\mathcal{C} \leftarrow \mathcal{B}}$  and  $P_{\mathcal{B} \leftarrow \mathcal{C}}$ .
4. Consider the set  $V = \left\{ f : \mathbb{R} \rightarrow \mathbb{R} : f(x) = \frac{c_1 x + c_2}{(x-1)(x-2)} \text{ for some } c_1, c_2 \in \mathbb{R} \right\}$ .
- Show that  $V$  is a subspace of the space of all functions.
  - One basis for  $V$  is  $\mathcal{B} = \left\{ \frac{1}{(x-1)(x-2)}, \frac{x}{(x-1)(x-2)} \right\}$ . Another is  $\mathcal{C} = \left\{ \frac{1}{x-1}, \frac{1}{x-2} \right\}$ . Compute the change of basis matrix  $P_{\mathcal{C} \leftarrow \mathcal{B}}$ .
  - Using part b), the fact that

$$\int \frac{A}{x-1} + \frac{B}{x-2} dx = A \log |x-1| + B \log |x-2| + C,$$

and the equation  $[\mathbf{v}]_{\mathcal{C}} = P_{\mathcal{C} \leftarrow \mathcal{B}}[\mathbf{v}]_{\mathcal{B}}$ , effortlessly compute the following integrals:

$$\int \frac{2x+1}{(x-1)(x-2)} dx, \quad \int \frac{3x-8}{(x-1)(x-2)} dx.$$

5. For the problems below, determine the component vector of the given vector in the vector space  $V$  relative to the given ordered basis  $\mathcal{B}$ .

- a)  $V = \mathbb{R}^3$ ;  $\mathcal{B} = \{(1, 0, 1), (1, 1, -1), (2, 0, 1)\}$ ;  $\mathbf{v} = (-9, 1, -8)$ .
- b)  $V = P_2(\mathbb{R})$ ;  $\mathcal{B} = \{5 - 3x, 1, 1 + 2x^2\}$ ;  $p(x) = 15 - 18x - 30x^2$ .
- c)  $V = M_{2 \times 2}(\mathbb{R})$ ;  $\mathcal{B} = \left\{ \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right\}$ ;  $A = \begin{bmatrix} -3 & -2 \\ -1 & 2 \end{bmatrix}$ .

### The Rank Nullity Theorem

6. Use the reduced row echelon form computed in HW2 to find a basis for  $\text{colspace}(A)$ , where

$$A = \begin{bmatrix} 2 & 4 & 1 & 11 & 14 \\ 1 & 2 & 1 & 8 & 10 \\ 4 & 8 & 2 & 22 & 28 \end{bmatrix}.$$

7. For the problems below, determine the nullity of  $A$  “by inspection” by appealing to the Rank-Nullity Theorem. Avoid computations.

a)  $A = \begin{bmatrix} 2 & -3 \\ 0 & 0 \\ -4 & 6 \\ 22 & -33 \end{bmatrix}$ .

b)  $A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ .

c)  $A = \begin{bmatrix} 0 & 0 & 0 & -2 \end{bmatrix}$ .

### Differential Equations

8. Consider the set  $V = \{f : \mathbb{R} \rightarrow \mathbb{R} : f'' - f = 0\}$  of solutions to the ODE  $f'' = f$ .
- Show that  $e^x$ ,  $e^{-x}$ ,  $\sinh x$ , and  $\cosh x$  are all elements of  $V$ .
  - Show that the lists of vectors  $\{e^x, e^{-x}\}$  and  $\{\sinh x, \cosh x\}$  are each linearly independent.
  - It can be shown that  $V$  is a two-dimensional vector space (accept this for now), so that  $\mathcal{B} = \{\cosh x, \sinh x\}$  and  $\mathcal{C} = \{e^x, e^{-x}\}$  are bases for  $V$ .
  - Let  $u(x)$  be the solution to the initial value problem

$$u''(x) - u(x) = 0, \quad u(0) = 5, \quad u'(0) = -2.$$

Pick one of the bases above and write  $u$  as a linear combination of the basis elements.

COMMENT: The calculations in d) are noticeably simpler in one of the bases—that’s the point!

9. Recall the equation (HW4) for the position  $y(t)$  of a spring-mass system with a damping force:

$$y'' + \frac{c}{m}y' + \frac{k}{m}y = 0, \quad (1)$$

where  $c > 0$  is the damping constant and  $k > 0$  is the spring constant. Let  $E(t) = \frac{1}{2}my'^2 + \frac{1}{2}ky^2$  be the total (potential plus kinetic) energy.

- a) Without solving the differential equation, show that  $E'(t) \leq 0$ .
- b) Use this to show that if  $y(0) = 0$  and  $y'(0) = 0$ , then  $y(t) = 0$  for all  $t \geq 0$ .
- c) Suppose that  $u(t)$  and  $v(t)$  both satisfy equation (1), and also  $u(0) = v(0)$  and  $u'(0) = v'(0)$ . Show that  $u(t) = v(t)$  for all  $t \geq 0$ .
- d) Show that the set of functions  $V = \left\{ f : \mathbb{R} \rightarrow \mathbb{R} : f'' + \frac{c}{m}f' + \frac{k}{m}f = 0 \right\}$  is a vector space.