

Chapter 8 and 9. ODE.

ODE ordinary differential equation
equation involving derivatives of
a function.

$$y(t) \quad y'(t), \quad y''(t), \quad y'''(t), \quad \dots \quad y^{(n)}(t)$$
$$\frac{d}{dt} y(t), \quad \frac{d^2}{dt^2} y(t), \quad \frac{d^n}{dt^n} y(t).$$

$$D = \frac{d}{dt}, \quad y'(t) = Dy.$$

$$y''(t) = D^2 y, \quad y^{(n)}(t) = D^n y.$$

Linear differential equations:

$$\text{Ex: } y''(t) + 2y'(t) + y(t) = 0.$$

$$y''(t) + 2y'(t) + y(t) = \sin t.$$

$$\text{General form: } a_0(t) \cdot y^{(n)}(t) + a_1(t) \cdot y^{(n-1)}(t) + \dots$$

divide $a_0(t)$ \rightarrow
on both sides if $a_0(t) \neq 0$.
 $+ a_n(t) \cdot y(t) = F(t).$

Goal: Solve this equation.

With initial condition

$$\begin{matrix} \nearrow \\ y^{(n-1)}(t_0) = c_1, \quad y^{(n-2)}(t_0) = c_2, \quad \dots \quad y(t_0) = c_n. \end{matrix}$$

This is called initial value problem.

Usually we focus on $a_0(t) = 1$.

(Defn) Linear differential operator of order n .

$$L = D^n + a_1(t)D^{n-1} + a_2(t)D^{n-2} + \dots + a_n(t)$$

$\leftarrow L$ has order n .

$$Ly = y^{(n)} + a_1(t)y^{(n-1)} + \dots + a_n(t)y.$$

(Goal) Solve $Ly = F(t)$ (*)

when $a_1(t), a_2(t), \dots, a_n(t)$
are constants.

Want to study (*) from the point of view
of linear algebra.

(compare $(*)$ with $Ax = b$.)

First view L as a linear transformation.

$V = \{ \text{functions of } t \text{ with derivatives of} \\ \text{all orders } \}. \text{ (smooth functions)}$

L is a linear transformation from V to V

$$L = D^2 + 2D + 1.$$

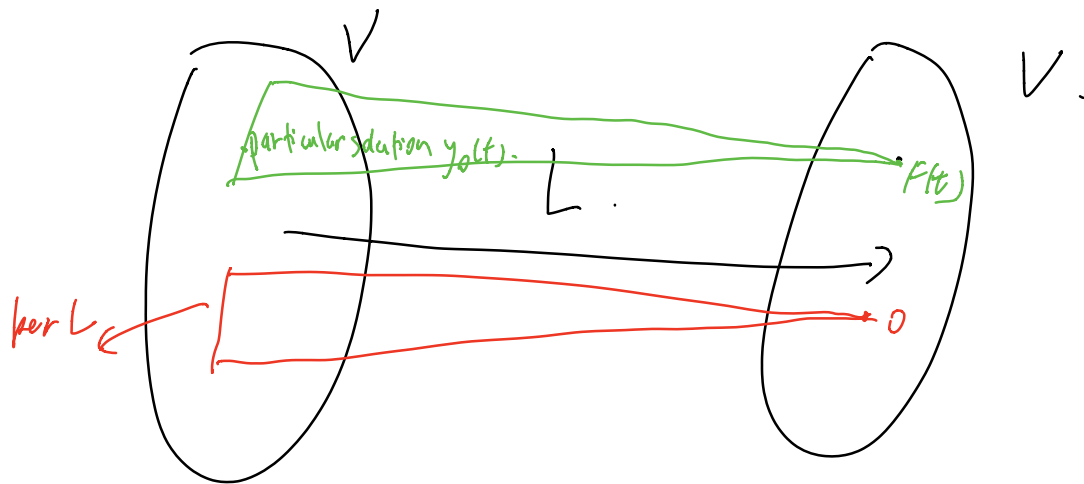
$$L: V \longrightarrow V.$$

$$y(t) \mapsto L(y(t)) = y''(t) + 2y'(t) + y(t)$$

Check: L is a linear transformation.

$$L(y_1 + y_2) = Ly_1 + Ly_2.$$

$$L(c \cdot y) = c \cdot Ly.$$



$$L y(t) = F(t) \quad (*)$$

Thm: If $y_0(t)$ is a particular solution to $(*)$,
 then all the solutions to $(*)$ has
 the form $y(t) = y_0(t) + x(t)$.

$x(t)$ is a solution to homogeneous
 equation $L(x(t)) = 0$
 in $\ker L$.

Two Steps

(1) Find $\ker L$.

Solve homogeneous equation

$$L y = 0.$$

Chapter B.2

(2) Find one particular solution $y_0(t)$. chapter 8.3
8.4.

Today: ①. homogeneous equation.

$$Ly = 0.$$

$$\text{Ex: } L = D^2 + 2D + 1. \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \begin{array}{l} (= D^2 + 2tD + 3t^2) \\ y''(t) + y'(t) + y(t) = 0. \\ \hline y'' + 2ty' + 3t^2y = 0 \end{array}$$

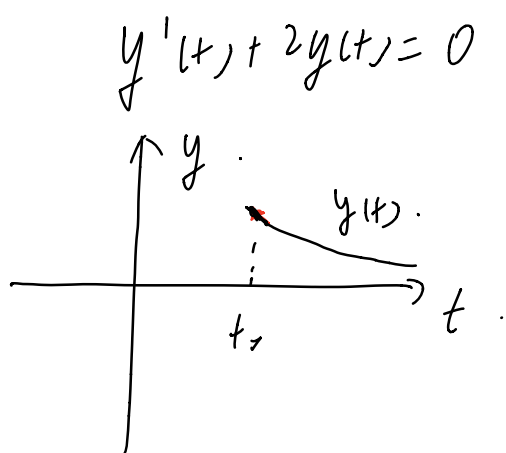
Black Box Theorem: (*) $Ly = F(t)$
(Existence + uniqueness).

(*) has a unique solution for any fixed
initial conditions

$$y^{(h-1)}(t_0) = c_1, \quad y^{(h-2)}(t_0) = c_2,$$

$$\dots \quad y(t_0) = c_n.$$

Ex of the theorem:



initial condition

$$\underline{y(t_0) = 1.}$$

$$\Rightarrow y'(t_0) = -2.$$

From the black box thm:

Thm for $Ly = 0$.

L has order n .

$$L = D^n + a_1(t)D^{n-1} + \dots + a_n(t)$$

($\ker L$ is a subspace of V)

$\ker L$ has $\dim = n$.

Thm tells us we should find

n linearly independent solutions to $Ly = 0$.

(basis of $\ker L$)

all the solutions are linear combinations.

Ex: ① $L = D - 2t$.

$$Ly = 0.$$

$$\boxed{\begin{array}{l} D + a_1(t) \\ e^{\int a_1(t)} \end{array}}$$

$$(D - 2t)y = 0 \Rightarrow y' - 2ty = 0.$$

(multiply both sides by $e^{\int -2t} = e^{-t^2}$.)

$$\underline{e^{-t^2}}(y' - 2t \cdot y) = 0.$$

$$e^{-t^2}y' + \underline{e^{-t^2} \cdot (-2t)}y = 0.$$

$$\Downarrow$$
$$(e^{-t^2})'$$

$$(e^{-t^2}y)' = 0.$$

$$e^{-t^2}y = c.$$

$$y = c \cdot e^{t^2}$$

ker L is 1-dim' (with basis $\{e^{2t}y\}$).

$$b). L = D^2 - 4$$

$$Ly = y''(t) - 4y(t) = 0.$$

Assume $y(t) = e^{rt}$ (*) Guess.

$$Dy = r e^{rt}, \quad D^2y = r^2 e^{rt}$$

$$r^2 e^{rt} - 4 e^{rt} = 0 \Rightarrow r^2 = 4.$$

$$r = \pm 2, \quad y_1(t) = e^{2t}$$

$$y_2(t) = e^{-2t}.$$

$\{y_1, y_2\}$ is linearly independent \Leftarrow (**).
hence basis of ker L .

any solution has the form

$$y(t) = c_1 e^{2t} + c_2 e^{-2t}.$$

Wronskian (Method to prove functions are linearly independent)

$$y_1(t), y_2(t).$$

$$\begin{cases} C_1 y_1(t) + C_2 y_2(t) = 0 \\ C_1 y_1' + C_2 y_2' = 0 \end{cases} \quad \downarrow \text{ derivative.}$$

$$\begin{bmatrix} y_1 & y_2 \\ y_1' & y_2' \end{bmatrix} \cdot \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

$$\text{Wronskian} = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = W(y_1, y_2)$$

If $W(y_1, y_2) \neq 0$, then $\{y_1, y_2\}$ is linearly independent. \swarrow for some t .

$$\text{Ex: } y_1(t) = e^{2t}, \quad y_2 = e^{-2t}$$

$$W(y_1, y_2) = \begin{vmatrix} e^{2t} & e^{-2t} \\ 2e^{2t} & -2e^{-2t} \end{vmatrix} = -2 - 2 = -4 \neq 0.$$

$$y_1(t), y_2(t), y_3(t).$$

$$\begin{cases} c_1 y_1 + c_2 y_2 + c_3 y_3 = 0 \\ c_1 y_1' + c_2 y_2' + c_3 y_3' = 0 \\ c_1 y_1'' + c_2 y_2'' + c_3 y_3'' = 0 \end{cases} \begin{array}{l} \nearrow \text{derivative} \\ \nearrow \text{derivative} \end{array}$$

$$\text{If } W(y_1, y_2, y_3) = \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix} \neq 0 \text{ for}$$

some t , then $\{y_1, y_2, y_3\}$ is linearly independent.

$$c) \cdot L = D^2 + 4.$$

$$Ly = y'' + 4y = 0.$$

$$\boxed{\text{Assume } y(t) = e^{rt}}$$

$$y'' = r^2 e^{rt}$$

$$r^2 e^{rt} + 4 e^{rt} = 0$$

$$\underline{r^2 + 4 = 0.} \quad r^2 = -4.$$

$$r = \pm \sqrt{-4} = \pm 2\sqrt{-1}$$

$$i = \sqrt{-1}.$$

imaginary number.

Euler's formula.

$$e^{\sqrt{-1}\theta} = \cos \theta + \sqrt{-1} \sin \theta.$$

$$y_1(t) = e^{2\sqrt{-1}t} = \boxed{\cos 2t} + \sqrt{-1} \boxed{\sin 2t}$$

$$y_2(t) = e^{-2\sqrt{-1}t} = \cos(-2t) + \sqrt{-1} \sin(-2t) \\ = \boxed{\cos 2t} - \sqrt{-1} \boxed{\sin 2t}.$$

real solutions.

$$\left\{ \begin{array}{l} \cos 2t = \frac{y_1 + y_2}{2} \\ \sin 2t = \frac{y_1 - y_2}{2\sqrt{-1}} \end{array} \right.$$

$$\text{Next: } W(\cos 2t, \sin 2t) = \begin{vmatrix} \cos 2t & \sin 2t \\ -2\sin 2t & 2\cos 2t \end{vmatrix}$$

$$= 2(\cos 2t)^2 + 2(\sin 2t)^2 = 2 \neq 0$$

$\{ \cos 2t, \sin 2t \}$ linearly independent.

hence basis of $\ker L$

general solution.

$$y(t) = C_1 \cos 2t + C_2 \sin 2t.$$

① Prove $\dim \ker L = \text{order of } L$.

② L has constant coefficients.

how to find n linearly independent solutions

① Pf: We construct a linear transformation

from $\ker L \xrightarrow{T} \mathbb{R}^n$.

$$T: \underline{\ker L} \rightarrow \mathbb{R}^n$$

$$y(t) \mapsto T(y) = \begin{pmatrix} y(t_0) \\ y'(t_0) \\ y''(t_0) \\ \vdots \\ y^{(n-1)}(t_0) \end{pmatrix}$$

Check T is a linear transformation.

Rk - Nullity Thm:

$$\dim \ker L = \underbrace{\dim \ker T}_0 + \underbrace{\dim \text{Image } T}_n.$$

① $\dim \ker T$. $\ker T = \left\{ y \mid \begin{array}{l} Ly = 0 \\ T(y) = 0 \end{array} \right\}$

$\left\{ \begin{array}{l} Ly = 0 \\ y(t_0) = 0, y'(t_0) = 0, \dots, y^{(n-1)}(t_0) = 0. \end{array} \right.$

black box theorem (uniqueness) $\Rightarrow y(t) = 0$.

$\ker T = \{0\}$. $\dim = 0$

② $\dim \text{Image } T$.

black box thm (Existence)

For any initial conditions

$$y(t_0), y'(t_0), \dots, y^{(n-1)}(t_0)$$

there exists $y(t)$. $L(y) = 0$.

$\Rightarrow \text{Image } T = \mathbb{R}^n$. $\dim = n$.

