

Question 3

A 4×4 matrix.

has e-values $\lambda_1 = 2$.

$\lambda_2 = -2$

$\lambda_3 = -2$

$\lambda_4 = 0$

(1) $Av = v$ has a solution v . **True.**

$v = 0$ is a solution.

(2) A is invertible **False**

$\lambda_4 = 0 \Rightarrow$ A is not invertible

$\det A = \lambda_1 \lambda_2 \lambda_3 \lambda_4 = 0$

A not invertible \Leftrightarrow one of e-values is $= 0$.

(3) $\det A = -2$ **False.**

$\det A = 0$

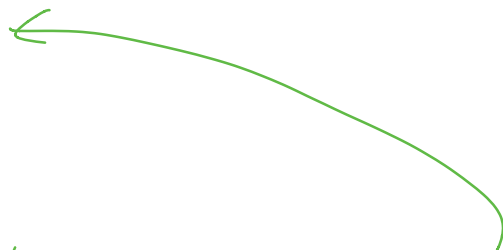
(4) algebraic multiplicities are 1, **2**, 1.
True. $\lambda_1 = 2, \lambda_2 = \lambda_3 = -2, \lambda_4 = 0$

⑤. A is diagonalizable (Not defective)

depends.

$$A = \begin{bmatrix} 2 & & & \\ & -2 & & \\ & & -2 & \\ & & & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 2 & & & \\ & -2 & & \\ & & 1 & \\ & & & -2 \\ & & & & 0 \end{bmatrix}$$



increase the rank of $A+2I$.
not diagonalizable.

⑥. $Ax=0$ has infinitely many solutions

True.

$\lambda = 0$ ϵ -value.

⑦. $\text{rk } A = 4$ False.

$\text{rk } A = 4 - \text{nullity of } A = 3$.

$\lambda = 0$ algebraic multiplicity \geq geometric multiplicity
" " " " " "

$$\textcircled{8} \quad \text{tr } A = \lambda_1 + \lambda_2 + \lambda_3 + \lambda_4 = 2 - 2 - 2 + 0 \\ = -2.$$

$$\textcircled{9} \quad \text{nullity } A = 1.$$

$\textcircled{10}$ $A^2 v = \pm v$ has at least two linearly independent solutions.

True

$$(Av = \pm 2v)$$

$$\lambda_1 = 2 \quad v_1 \in \mathbb{C}\text{-space}$$

$$\lambda_2 = \lambda_3 = -2 \quad v_2 \in \mathbb{C}\text{-space}.$$

$\{v_1, v_2\}$ linearly independent.

Question \forall A $n \times n$

$A^T A$ invertible $(\Leftrightarrow) A$ invertible.

$$\text{Pf: } \det(A^T A) = (\det A^T)(\det A)$$

$$= (\det A)^2 \\ \det(A^T A) \neq 0 \Leftrightarrow \det A \neq 0.$$

O/D/E .

Outline:

① L linear differential operator. $y(x)$

$Ly = 0$. homogeneous .

solution space is a vector space .

dim = order of $L \geq n$

② L first order

$$L = D + a_1(x)$$

$$y' + a_1(x)y = 0$$

Integration factor $e^{\int a_1(x)}$ (multiply on both sides)

$$y' e^{\int a_1(x)} + a_1(x) \cdot y \cdot e^{\int a_1(x)} = 0$$

$$(y e^{\int a_1(x)})' = 0 \text{ solve } y$$

③ Wronskian of y_1, y_2, \dots, y_n .

$$\begin{vmatrix} y_1 & \dots & y_n \\ y_1' & \dots & y_n' \\ \vdots & & \vdots \\ y_1^{(n-1)} & \dots & y_n^{(n-1)} \end{vmatrix} = W(y_1, y_2, \dots, y_n)$$

If $W \neq 0$ at some point, then
 $\{y_1, \dots, y_n\}$ linearly independent.

Solve $Ly = 0$ with constant coefficients.

Basic idea is to use

$$y(x) = e^{rx}$$

and determine r .

2nd-order ODE.

$$y'' + a_1 y' + a_2 y = 0. \quad (*)$$

$a_1, a_2 \in \mathbb{R}$ constants.

Guess $y(x) = e^{rx}$ is a solution.

$$y' = r e^{rx}$$

$$y'' = r^2 e^{rx}$$

$$(*) \Rightarrow (r^2 + a_1 r + a_2) e^{rx} = 0$$

$$\underline{r^2 + a_1 r + a_2 = 0.}$$

$$r = \frac{-a_1 \pm \sqrt{a_1^2 - 4a_2}}{2}$$

Three different cases

Case 1. 2 real distinct roots. $a_1^2 - 4a_2 > 0$.

$$r_1 = \frac{-a_1 + \sqrt{a_1^2 - 4a_2}}{2}, \quad r_2 = \frac{-a_1 - \sqrt{a_1^2 - 4a_2}}{2}$$

$$y_1(x) = e^{r_1 x} \quad y_2 = e^{r_2 x}$$

Need to check Wronskian.

$$\begin{aligned} W(y_1, y_2) &= \begin{vmatrix} e^{r_1 x} & e^{r_2 x} \\ r_1 e^{r_1 x} & r_2 e^{r_2 x} \end{vmatrix} \\ &= r_2 e^{(r_1+r_2)x} - r_1 e^{(r_1+r_2)x} \\ &= (r_2 - r_1) e^{(r_1+r_2)x} \neq 0 \\ &\quad (r_2 \neq r_1) \end{aligned}$$

All the solutions $y(x) = C_1 y_1 + C_2 y_2$.

$$= C_1 e^{r_1 x} + C_2 e^{r_2 x}$$

Case 2: One repeated root. $a_1^2 - 4a_2 = 0$

$$r_1 = r_2 = \frac{-a_1 \pm \sqrt{a_1^2 - 4a_2}}{2} = -\frac{a_1}{2}$$

Find one solution $y_1(x) = e^{rx}$. $r = -\frac{a_1}{2}$.

How to find the other solution

$$\frac{r^2 + a_1 r + a_2 = 0}{(r + \frac{a_1}{2})^2 = 0}$$

$$(D^2 + a_1 D + a_2) = (D + \frac{a_1}{2})^2$$

$$(D + \frac{a_1}{2}) \left[\underbrace{(D + \frac{a_1}{2}) y(x)}_{z(x)} \right] = 0$$

$$(D + \frac{a_1}{2}) z(x) = 0$$

$$z'(x) + \frac{a_1}{2} z(x) = 0 \quad \text{multiply } e^{\int \frac{a_1}{2} dx}$$
$$= e^{\frac{a_1}{2} x}$$

$$\underbrace{z'(x) \cdot e^{\frac{a_1}{2} x} + \frac{a_1}{2} \cdot e^{\frac{a_1}{2} x} \cdot z(x)} = 0$$

$$(z(x) \cdot e^{\frac{a_1}{2} x})' = 0$$

$$z'(x) \cdot e^{\frac{a_1}{2}x} = C_1$$

$$z(x) = C_1 e^{-\frac{a_1}{2}x}$$

//

$$(D + \frac{a_1}{2})y(x) = C_1 e^{-\frac{a_1}{2}x}$$

multiply $e^{\frac{a_1}{2}x}$

$$y' e^{\frac{a_1}{2}x} + \frac{a_1}{2} e^{\frac{a_1}{2}x} y(x) = C_1$$

$$(y e^{\frac{a_1}{2}x})' = C_1$$

$$y e^{\frac{a_1}{2}x} = C_1 x + C_2$$

$$y(x) = \underbrace{C_1 x \cdot e^{-\frac{a_1}{2}x} + C_2 e^{-\frac{a_1}{2}x}}$$

$$\left\{ \begin{array}{l} y_1(x) = e^{-\frac{a_1}{2}x} = e^{r_1 x} \end{array} \right.$$

$$\left\{ \begin{array}{l} y_2(x) = x \cdot e^{-\frac{a_1}{2}x} = x \cdot e^{r_1 x} \end{array} \right.$$

$$e^{r_1 x}, x e^{r_1 x}$$

$$r_1 = r_2 = -\frac{a_1}{2}$$

Case 3. $\frac{a_1^2 - 4a_2 < 0}{2}$ two complex roots

$$r = \frac{-a_1 \pm \sqrt{a_1^2 - 4a_2}}{2} = \frac{-a_1 \pm \sqrt{4a_2 - a_1^2} i}{2}$$

$$i^2 = -1.$$

$$r_1 = \alpha + \beta i, \quad r_2 = \alpha - \beta i.$$

$$\alpha = -\frac{a_1}{2}, \quad \beta = \frac{\sqrt{4a_2 - a_1^2}}{2}$$

$$y_1(x) = e^{r_1 x}, \quad y_2(x) = e^{r_2 x}$$

Wronskian $(y_1, y_2) \neq 0$

Euler's identity:

$$y_1(x) = e^{(\alpha + \beta i)x} = e^{\alpha x} \cdot e^{\beta x i}$$

$$= e^{\alpha x} \cdot (\cos \beta x + i \sin \beta x)$$

$$y_2(x) = e^{\alpha x} \cdot e^{-\beta x i}$$

$$= e^{\alpha x} (\cos \beta x - i \sin \beta x)$$

$$\frac{y_1 + y_2}{2} = e^{\alpha x} \cos \beta x$$

$$\frac{y_1 - y_2}{2i} = e^{\alpha x} \sin \beta x$$

Basis of $\{Ly = 0\}$

Summary: If $L = D^2 + a_1 D + a_2$

- (case 1) $a_1^2 - 4a_2 > 0$, $r^2 + a_1 r + a_2 = 0$
has two real distinct roots r_1, r_2

$\{e^{r_1 x}, e^{r_2 x}\}$ is a basis of $\ker L$

- (case 2), $a_1^2 - 4a_2 = 0$, $r^2 + a_1 r + a_2 = (r - r_1)^2$

$\{e^{r_1 x}, x e^{r_1 x}\}$ is a basis of $\ker L$

- (case 3), $a_1^2 - 4a_2 < 0$, $r^2 + a_1 r + a_2 = (r - (\alpha + \beta i))(r - (\alpha - \beta i))$

$\{e^{2x} \cos px, e^{2x} \sin px\}$ is a basis
of $\ker L$.

Example: $y'' + 6y' + 25 = 0$.

$$r^2 + 6r + 25 = 0 \Rightarrow$$

$$r = \frac{-6 \pm \sqrt{36 - 25 \cdot 4}}{2} = -3 \pm 4i.$$

$$\sqrt{36 - 100} = \sqrt{-64} = 8i.$$

$$y(x) = C_1 e^{-3x} \cos 4x + C_2 e^{-3x} \sin 4x$$

Higher order equations:

The method generalizes to

$$a) \quad y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y' + a_n = 0.$$

$$L = D^n + a_1 D^{n-1} + \dots + a_{n-1} D + a_n$$

Try solutions $y(x) = e^{rx}$

$$r^n + a_1 r^{n-1} + \dots + a_{n-1} r + a_n$$

(Defn) Auxiliary polynomial. $P(r)$

$$P(r) = 0 \quad \text{aux. equation.}$$

$$P(r) = (r-r_1)^{m_1} (r-r_2)^{m_2} \dots (r-r_k)^{m_k}$$

$m_1 + m_2 + \dots + m_k = n$, r_1, \dots, r_k are complex numbers.

$$L = (D-r_1)^{m_1} (D-r_2)^{m_2} \dots (D-r_k)^{m_k}$$

r_1, \dots, r_k complex numbers

• Case 1 r_1 real number.

$(D-r_1)^{m_1}$ has solutions

$$\underbrace{e^{r_1 x}, x e^{r_1 x}, x^2 e^{r_1 x}, \dots, x^{m_1-1} e^{r_1 x}}$$

m_1 linearly independent solutions

Other real roots contribute similar solutions.

Case 2. If $r_1 = \alpha + \beta i$. $i^2 = -1$
 then $\bar{r}_1 = \alpha - \beta i$ is also a
 solution.

$(D - r_1)^{m_1} (D - \bar{r}_1)^{m_1}$ has solutions

$$e^{\alpha x} \cos \beta x, \quad e^{\alpha x} \sin \beta x,$$

$$x e^{\alpha x} \cos \beta x, \quad x e^{\alpha x} \sin \beta x$$

$$\vdots$$

$$x^{m_1-1} e^{\alpha x} \cos \beta x, \quad x^{m_1-1} e^{\alpha x} \sin \beta x.$$

$2m_1$ linearly independent solutions.

Collect all the solutions to

$$(D - r_i)^{m_i} \quad \text{or}$$

$$(D - r_i)^{m_i} (D - \bar{r}_i)^{m_i}.$$

we get a basis of $\{Ly = 0\}$

Ex: $y^{(k)}(x) - c y = 0, \quad c > 0.$

Aux. equation: $r^k - c = 0.$

$$(r^2 + \sqrt{c})(r^2 - \sqrt{c})$$

$$= (r + c^{\frac{1}{k}})(r - c^{\frac{1}{k}})(r + c^{\frac{1}{k}}i)(r - c^{\frac{1}{k}}i)$$

$$r_1 = -c^{\frac{1}{k}}, \quad r_2 = c^{\frac{1}{k}}, \quad \underbrace{r_3 = c^{\frac{1}{k}}i, \quad r_4 = c^{\frac{1}{k}}i}_{\substack{2 + \beta i, \text{ complex} \\ 2 - \beta i \text{ conjugate.}}}$$

$$y(x) = C_1 e^{-c^{\frac{1}{k}}x} + C_2 e^{c^{\frac{1}{k}}x}$$

$$+ C_3 \cos(c^{\frac{1}{k}}x) + C_4 \sin(c^{\frac{1}{k}}x)$$

Initial conditions.

Ex: $y'' + ky' + ky = 0, \quad \underbrace{y(0) = 1, \quad y'(0) = k.}_{}$

$$\begin{aligned}\text{Aux. poly: } r^2 + 4r + 4 \\ = (r+2)^2.\end{aligned}$$

$$y(x) = C_1 e^{-2x} + C_2 x \cdot e^{-2x}$$

$$\left\{ \begin{aligned} y(0) &= C_1 + C_2 \cdot 0 = C_1 = 1 \end{aligned} \right.$$

$$\left\{ \begin{aligned} y'(0) &= C_1 \cdot (-2) e^{-2x} \Big|_{x=0} + C_2 (e^{-2x} + -2x e^{-2x}) \Big|_{x=0} \\ &= -2C_1 + C_2 = 4. \end{aligned} \right.$$

$$C_1 = 1, \quad C_2 = 6.$$

$$y(x) = e^{-2x} + 6x e^{-2x}$$