

Inhomogeneous equations + Annihilator method.

Recall: $P(D) = D^n + a_1 D^{n-1} + \dots + a_n$

a_1, \dots, a_n constant.

How to solve?

Aux. polynomial $P(r) = r^n + a_1 r^{n-1} + \dots + a_n$.

Solve $P(r) = 0$. Real root r , or
complex root $r = \alpha + \beta i$.

solutions are $e^{rx}, xe^{rx}, x^2 e^{rx}, \dots$
 $e^{\alpha x} \cos \beta x, x e^{\alpha x} \cos \beta x, \dots$
 $e^{\alpha x} \sin \beta x, x e^{\alpha x} \sin \beta x, \dots$

(Goal: Solve $P(D)y = \underbrace{F(x)}_{\neq 0}$ (*)

in homogeneous.

Solutions are of the form

$$y(x) = \underbrace{y_p(x)}_{P(D)y_p = F} + \underbrace{y_c(x)}_{P(D)y_c = 0}$$

basis
vector space.

Annihilator method.

Suppose we can find a polynomial operator

$$A(D) \text{ s.t. } A(D)F = 0.$$

Then $\underline{A(D)P(D)y = A(D)F(x) = 0} \text{ (**)}$

Solve the homogeneous equation.

(But not every solution of (**))

is a solution of (*).

$$A(D)\square = 0 \text{ does not mean } \square = F(x)$$

Ex: Solve $(D+3)(D-3)y = 10e^{2x}$.

Step 1: solve $(D+3)(D-3)y_c = 0$.

$$y_c = C_1 e^{3x} + C_2 e^{-3x}.$$

Step 2: Find.

$$\underline{A(D) \cdot (10 e^{2x}) = 0}$$

$$A(D) = D - 2.$$

$$\underline{A(D) \cdot P(D) \cdot y = 0}$$

$$(D-2)(D+3)(D-3) y = 0.$$

$$y = \frac{C_1 e^{3x} + C_2 e^{-3x} + A_0 e^{2x}}{y_c.}$$

General Theory tells us

$$y = \underbrace{y_c}_{C_1 e^{3x} + C_2 e^{-3x}} + \underbrace{y_p}_A$$

Step 3 Solve A_0 .

$$(A) \quad (D+3)(D-3)(A_0 e^{2x}) = 10 e^{2x}$$

$$\underline{(D^2 - 9)(A_0 e^{2x}) = 10 e^{2x}.}$$

/

$$\downarrow$$

$$A_0 (4 \cdot e^{2x} - 9 \cdot e^{2x}) = 10 e^{2x}$$

$$-5 A_0 = 10 \Rightarrow A_0 = -2.$$

$$y(x) = C_1 e^{3x} + C_2 e^{-3x} - 2 e^{2x}.$$

\downarrow
 y_p

Ex: Find the general solution to

$$*) (D-4)(D+1)y(x) = \underline{15 e^{4x}}$$

$$\text{Step 1: } (D-4)(D+1)y_c(x) = 0$$

$$\Rightarrow y_c(x) = C_1 e^{4x} + C_2 e^{-x}$$

Step 2: an annihilator $A(D)$ of e^{4x} is

$$A(D) = D-4$$

$$(D-4)(D-4)(D+1)y(x) = 0 \quad (**)$$

$$(D-4)^2(D+1)y(x) = 0$$

$$y_1(x) = \frac{C_1 e^{4x}}{\quad} + \frac{C_2 x e^{4x}}{\quad} + \frac{C_3 e^{-x}}{\quad}$$

$$y_c(x) = C_1 e^{4x} + C_2 e^{-x}$$

Step 3: $y_p = C_2 x e^{4x}$

determine C_2 ,

$$y_p' = C_2 \cdot (e^{4x} + 4x e^{4x})$$

$$y_p'' = C_2 \left(\underbrace{4e^{4x} + 4e^{4x}}_{8e^{4x}} + 16x e^{4x} \right)$$

$$(D-4)(D+1) = \underline{D^2 - 3D - 4}$$

$$(D-4)(D+1)y_p = C_2 \left(\begin{array}{l} 8e^{4x} + 16x e^{4x} \\ -3e^{4x} - 3 \cdot 4x e^{4x} \end{array} \right)$$

$$\begin{aligned}
 & - \underline{4 x e^{4x}} \\
 & = C_2 (5 e^{4x} - 0) \\
 & = 15 e^{4x}
 \end{aligned}$$

$$C_2 = 3. \quad y_p = 3 x e^{4x}$$

$$y(x) = C_1 e^{4x} + C_2 e^{-x} + 3 x e^{4x}$$

Summary: $P(D) y(x) = e^{r_0 x}$.

Apply $(D - r_0) = A(D)$ on both sides

$P(r)$ may have a root r_0 with ^{algebraic} multiplicity m .

has \rightarrow one more dim for solution space

$$P(D) y = \dots (D - r_0)^m \dots = 0$$

$$A(D) P(D) y = \dots (D - r_0)^{m+1} \dots = 0$$

particular solution: $A_0 x^m \cdot e^{r_0 x} = y_p(x)$

Solve A_0 by plug in $(*)$
 $y_p(x)$

Can also generalize to $f(x) = x^k \cdot e^{r_0 x}$

Ex: Find the general solution to

$$(*) \quad (D^2 - 4D + 5) y(x) = 7x e^{2x} \cos x$$

Step 1: Solve homogeneous equation.

$D^2 - 4D + 5$ has

Aux. poly $r^2 - 4r + 5 = 0$

$$r = \frac{4 \pm \sqrt{16 - 4 \cdot 5}}{2} = 2 \pm i.$$

$$y_c(x) = C_1 e^{2x} \cos x + C_2 e^{2x} \sin x.$$

Step 2: Annihilator for $x e^{2x} \cos x$
 $e^{2x} \cos px$ $\leftarrow r_0 = 2 + \beta i$

$$r_0 = 2 + i \quad \left| \quad \bar{r}_0 = 2 - i \right.$$

$$\left((D - r_0)(D - \bar{r}_0) \right)^2$$

$$= \left((D - (2 + i))(D - (2 - i)) \right)^2 \in$$

$$= (D^2 - 4D + 5)^2 = A(D)$$

$$A(D) \times e^{2x} \cos x = 0$$

apply $A(D)$ to $P(D)y = F(x)$ (*)

$$(**) (D^2 - 4D + 5)^3 y = 0 \quad \text{order} = 6$$

$$(D^2 - 4D + 5) y_c = 0 \quad \text{order} = 2.$$

4 more dims of solution space

$$y(x) = \underline{C_1 e^{2x} \cos x + C_2 e^{2x} \sin x} \rightarrow y_c.$$

$$\left. \begin{aligned} &+ A_0 x e^{2x} \cos x + B_0 x e^{2x} \sin x \\ &+ A_1 x^2 e^{2x} \cos x + B_1 x^2 e^{2x} \sin x. \end{aligned} \right\} \rightarrow y_p.$$

Step 3. plug y_p into $(*)$.

$$(D^2 - 4D + 5) \cdot y_p = 8x \cos x.$$

↓ lots of simplifications.

$$\frac{(-2A_0 + 2B_1 - 4x A_1) \sin x + (2B_0 + 2A_1 + 4x B_1) \cos x}{\downarrow} = 8x \cos x.$$

$$-2A_0 + 2B_1 = 0$$

$$-4A_1 = 0$$

$$2B_0 + 2A_1 = 0$$

$$4B_1 = 8.$$

$$\Rightarrow A_1 = 0 = B_0.$$

$$A_0 = B_1 = 2$$

$$y_p = 2xe^{2x} \cos x + 2x^2 e^{2x} \sin x.$$

$$y(x) = c_1 e^{2x} \cos x + c_2 e^{2x} \sin x + 2x e^{2x} \cos x + 2x^2 e^{2x} \sin x.$$

Annihilator method.

$$F(x) = x^k e^{r_0 x}$$

$$x^k e^{\alpha x} \cos \beta x$$

$$x^k e^{\alpha x} \sin \beta x.$$

$$\underline{\underline{A(D) F(x) = 0}}$$

order of $A(D)$ is m .

$$\left(\begin{array}{l} A(D) P(D) y = 0 \\ P(D) y_c = 0 \end{array} \right) \text{ compare}$$

get m more solutions in the bases
 ↓ of solution spaces

$$\text{Extra sol'n: } \underline{A_0 x e^{r_0 x} + A_1 x^2 e^{r_0 x} \dots} = y_p$$

solutions with m constant coefficients A_0, A_1, \dots

determine constants by plug in to (*).

Applications (to Spring-Mass System) (Chapter 8.5)



Spring constant (Hooke's law)

$$F = k \cdot y.$$

(damped) Spring-Mass equation: $y(t)$

$$m y'' + \overset{\text{damping constant}}{c} y' + \overset{\text{spring constant}}{k} y = 0$$

from

Newton's law $k, c > 0$ are positive constants
 $m > 0$

damped Spring mass equation with

external force: $F(t)$

(New equation)
$$y'' + \frac{c}{m} y' + \frac{k}{m} y = \frac{1}{m} F(t).$$

Notation
$$\omega_0 = \sqrt{\frac{k}{m}} \leftarrow \text{frequency}.$$

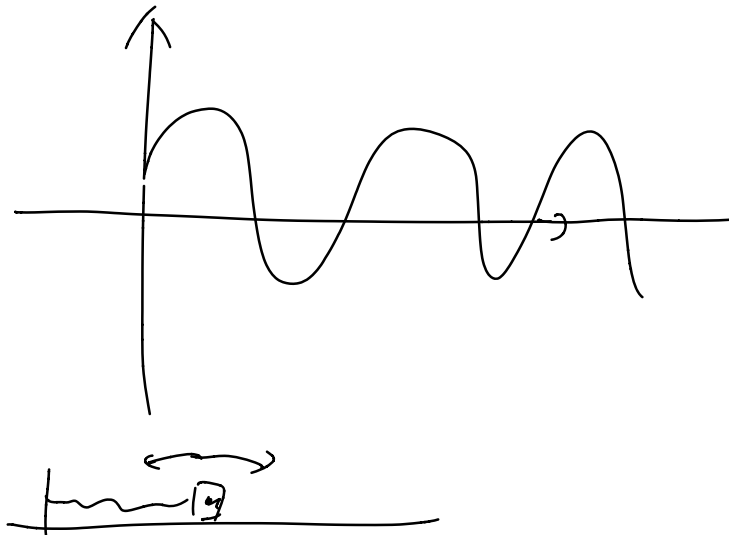
When $F = 0$.

1. No damping ($C = 0$)

$$y'' + \frac{k}{m} y = 0 \quad \underline{y'' + \omega_0^2 y = 0.}$$

Aux. poly $r^2 + \omega_0^2 = 0, \quad r = \pm i\omega_0.$

$$y(t) = C_1 \cos(\omega_0 t) + C_2 \sin(\omega_0 t)$$



2. Damping. $C > 0$.

$$y'' + \frac{c}{m} y' + \frac{k}{m} y = 0$$

$$r^2 + \frac{c}{m} r + \frac{k}{m} = 0.$$

$$\underline{\left(\frac{c}{m}\right)^2 - 4 \frac{k}{m}}$$

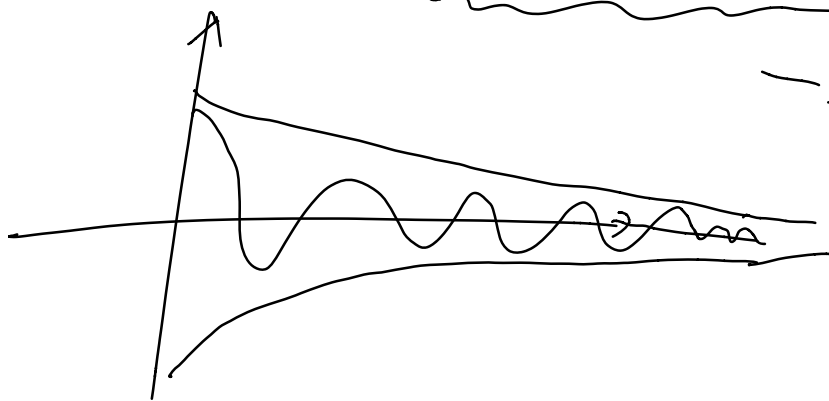
a) $\left(\frac{c}{m}\right)^2 - 4 \frac{k}{m} < 0, \Rightarrow c^2 < 4km. \text{ (under-damping)}$

$$r = \frac{-\frac{c}{m} \pm \sqrt{\left(\frac{c}{m}\right)^2 - 4 \frac{k}{m}}}{2}$$

$$= -\left(\frac{c}{2m} \pm \frac{\sqrt{4km - c^2}}{2m} i\right) \quad i^2 = -1.$$

$$\mu = \frac{\sqrt{4km - c^2}}{2m}.$$

$$y(t) = e^{-\frac{c}{2m}t} (C_1 \cos \mu t + C_2 \sin \mu t)$$



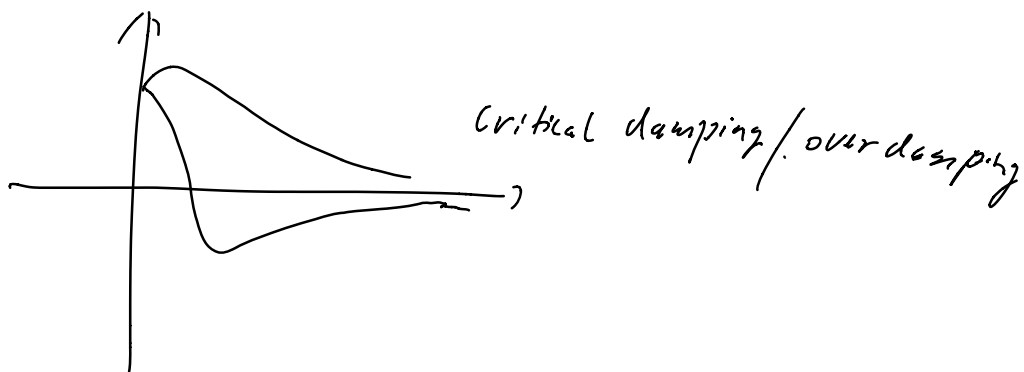
→ converge to zero.

$$b) \cdot \left(\frac{c^2}{m}\right) - \frac{4k}{m} = 0 \quad (\text{critical damping})$$

$$\rightarrow c^2 = 4km.$$

$$r = -\frac{c}{2m}$$

$$y(t) = e^{-\frac{c}{2m}t} (c_1 + c_2 t).$$



$$c) \quad c^2 > 4km \quad (\text{over damping})$$

$$y(t) = e^{-\frac{c}{2m}t} (c_1 e^{\mu t} + c_2 e^{-\mu t})$$

$$\mu = \frac{\sqrt{c^2 - 4km}}{2m}$$