

Spring-Mass system. (Oscillations of a Mechanical system)

- constants.

$$\text{ODE: } y'' + \left(\frac{c}{m}\right) y' + \left(\frac{k}{m}\right) y = \frac{1}{m} F(t) \quad (*)$$

$$y(t), \quad y(0) = y_0, \quad y'(0) = v_0.$$

Last time: external force $F(t) \equiv 0$.

Aux. poly: $r^2 + \frac{c}{m} r + \frac{k}{m} = 0$

Case 1: No damping. $c = 0$.

$$y(t) = C_1 \cos \omega_0 t + C_2 \sin \omega_0 t.$$

$$\omega_0 = \sqrt{\frac{k}{m}}.$$

$$= A_0 \cos(\omega_0 t - \alpha)$$

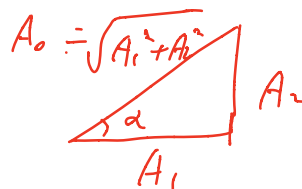
$$A_0 = \sqrt{C_1^2 + C_2^2}$$

Recall identities from trig.

$$A_1 \cos \theta + A_2 \sin \theta.$$

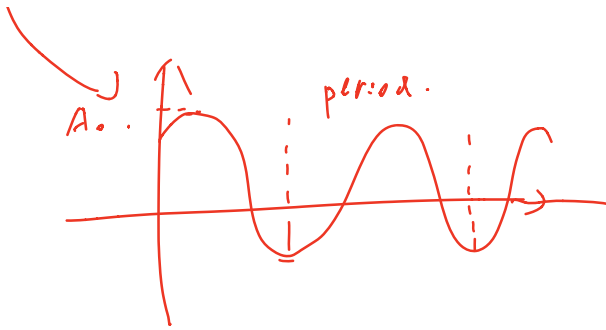
$$= A_0 (\cos \alpha \cos \theta + \sin \alpha \sin \theta)$$

$$= A_0 \cdot \cos(\theta - \alpha).$$

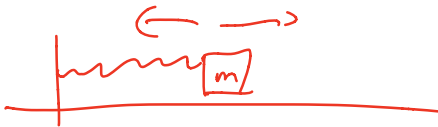


$$\cos \alpha = \frac{A_1}{\sqrt{A_1^2 + A_2^2}} = \frac{A_1}{A_0}$$

$$\sin \alpha = \frac{A_2}{A_0}$$



$$\text{period} = \frac{2\pi}{\omega_0} = 2\pi \sqrt{\frac{m}{k}}$$

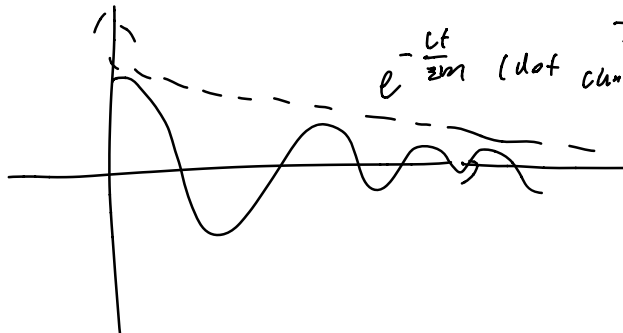


(case 2 Damping $c > 0$.

2.a) Under damped $(c^2 < 4km)$ Aux. polynomial
complex roots

$$y(t) = e^{-\frac{ct}{2m}} (c_1 \cos(\mu t) + c_2 \sin(\mu t))$$

$$\mu = \frac{\sqrt{4km - c^2}}{2m}$$



b) critically damped $c^2 = 4km$.

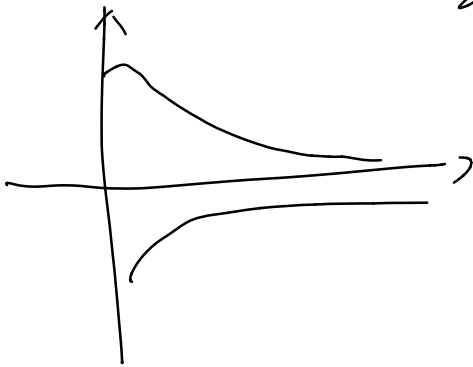
$$y(t) = e^{-\frac{ct}{2m}} (C_1 + C_2 t)$$

c) overdamped $c^2 > 4km$.

$$y(t) = e^{-\frac{ct}{2m}} (C_1 e^{\mu t} + C_2 e^{-\mu t})$$

$$\mu = \frac{\sqrt{c^2 - 4km}}{2m}$$

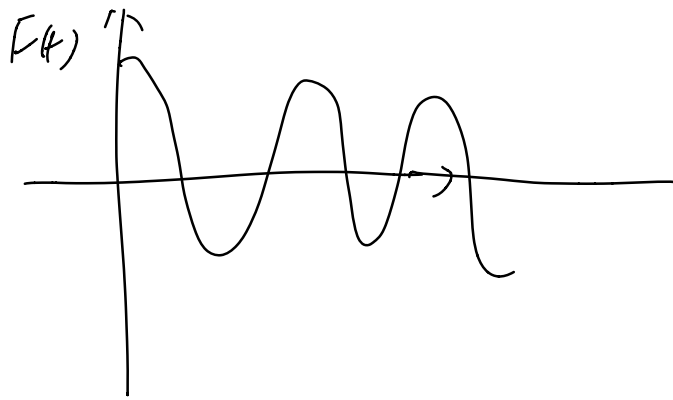
b) c)



$F(t) = 0$ homogeneous equation.

Today's class: we focus on

$$F(t) = F_0 \cos \omega t. \quad F_0, \omega \text{ are constants.}$$



$F(t)$ is periodic.

Case 1: No damping

homogeneous solutions:

$$y_c(t) = A_0 \cos(\omega_0 t - \phi)$$

$$y = y_c + y_p$$

Anni. of $F(t) = F_0 \cos \omega t$

$$\begin{aligned} A(D) &= (D - \omega i)(D + \omega i) \\ &= D^2 + \omega^2 \end{aligned}$$

$$P(D) = D^2 + \frac{c}{m} D + \frac{k}{m} = D^2 + \frac{k}{m}$$

$$\underline{A(D) P(D)}$$

If $\omega_0 \neq \omega$, i.e. $\frac{k}{m} \neq \omega^2$.

$$y_p = A_1 \cos \omega t + A_2 \sin \omega t \\ = C_0 \cdot \cos(\omega t - \alpha)$$

$$y_p'' + \frac{k}{m} y_p = \frac{F_0}{m} \cos \omega t.$$

$$C_0 \left(-\omega^2 + \frac{k}{m} \right) \cos(\omega t - \alpha) = \frac{F_0}{m} \cos \omega t$$

$$C_0 = \frac{F_0}{m(\omega_0^2 - \omega^2)}, \quad \alpha = 0$$

$$y_p = \frac{F_0}{m(\omega_0^2 - \omega^2)} \cos \omega t$$

General solution $y(x) = A_0 \cdot \cos(\omega_0 t - \phi) + \frac{F_0}{m(\omega_0^2 - \omega^2)} \cos \omega t.$

Look at case: $y(0) = y'(0) = 0.$

$$\text{get: } y(0) = 0 \Rightarrow A_0 \cos \phi + \frac{F_0}{m(\omega_0^2 - \omega^2)} = 0$$

$$y'(0) = 0 \Rightarrow A_0 \omega_0 \sin(-\phi) + \frac{F_0 \omega}{m(\omega_0^2 - \omega^2)} \sin 0 = 0$$

$$\Downarrow$$

$$\sin \phi = 0 \Rightarrow \phi = 0$$

$$A_0 + \frac{F_0}{m(\omega_0^2 - \omega^2)} = 0 \quad A_0 = \frac{-F_0}{m(\omega_0^2 - \omega^2)}$$

$$y(t) = \frac{F_0}{m(\omega_0^2 - \omega^2)} (\cos \omega t - \cos \omega_0 t)$$

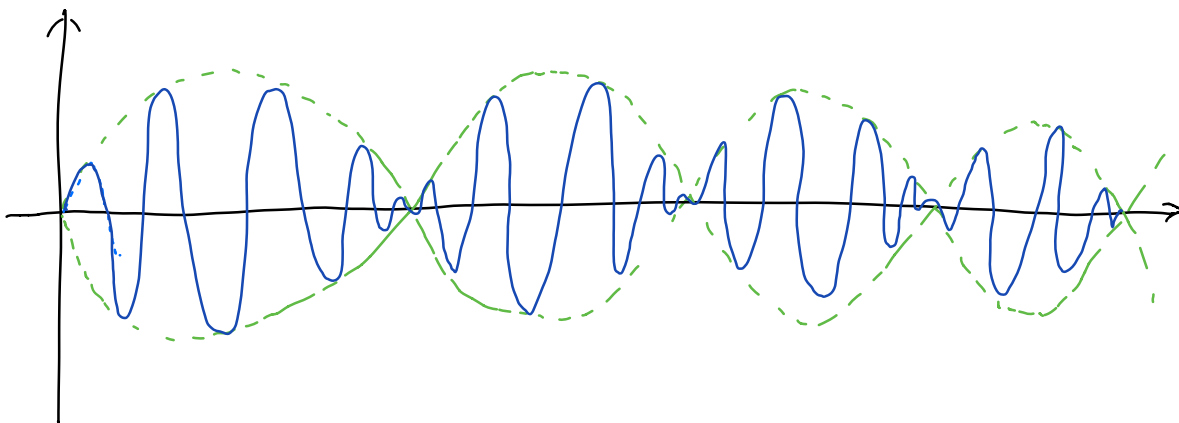
ω is related to $F(t)$ when $\omega = \omega_0$.
resonance
 ω_0 is related to Spring-Mass system itself.

Recall trig identity: $\cos(A-B) - \cos(A+B)$
 $= 2 \sin A \sin B.$

$$\begin{aligned} A-B &= \omega t, \\ A+B &= \omega_0 t \end{aligned} \Rightarrow \begin{cases} A = \frac{1}{2}(\omega_0 + \omega)t \\ B = \frac{1}{2}(\omega_0 - \omega)t. \end{cases}$$

$$y(t) = \frac{2F_0}{m(\omega_0^2 - \omega^2)} \underbrace{\sin\left(\frac{\omega_0 - \omega}{2}t\right)}_{\substack{\text{smaller} \\ \text{longer period.}}} \sin\left(\frac{\omega_0 + \omega}{2}t\right)$$

$\underbrace{\hspace{10em}}_{\substack{\text{not small} \\ \text{shorter period.}}}$



Resonance: $\omega = \omega_0$. $y'' + \omega_0^2 y = \frac{F_0}{m} \cos \omega_0 t$.

$$A(D) = (D^2 + \omega_0^2)$$

$$P(D) = (D^2 + \omega_0^2)$$

$A(D)P(D)$ has repeated complex roots

$$i\omega_0, -i\omega_0$$

↓
algebraic multiplicity 2.

$$\underline{y_p = t(A_1 \cos \omega_0 t + A_2 \sin \omega_0 t)}$$

$$(D^2 + \omega_0^2) y_p = \frac{F_0}{m} \cos \omega_0 t.$$

$$\Rightarrow A_1 = 0, \quad A_2 = \frac{F_0}{2k\omega_0}.$$

$$\text{General solution } y(t) = y_c + y_p$$

$$= A_0 \cos(\omega_0 t - \phi)$$

$$+ \frac{F_0}{2k\omega_0} t \sin \omega_0 t.$$

$t \rightarrow t\omega_0$.

eventually, the spring will break.

Damping $c > 0$.

$$y'' + \frac{c}{m} y' + \frac{k}{m} = \frac{F_0}{m} \cos \omega t.$$

Ans poly $r^2 + \frac{c}{m}r + \frac{k}{m} = 0$ has not
root $\pm \omega i$.

plug
in.

$$y_p(t) = A_1 \cos \omega t + A_2 \sin \omega t.$$

long calculation \Rightarrow

$$y_p(t) = \frac{F_0}{(k - m\omega^2)^2 + c^2\omega^2} \left[(k - m\omega^2) \cos \omega t + c\omega \sin \omega t \right]$$

general solution $y(x) = y_p + y_c$

$$c > 0 \Rightarrow \lim_{t \rightarrow \infty} y_c(t) \rightarrow 0$$

"transient part!"

steady state.

only see the part caused by external force.

New topic chapter 3.9.

Reduction of order method to find solutions

to 2nd order ODE gives one (non-zero) solution to homo eqn.

Study (x) $y'' + a_1(x)y' + a_2(x)y = f(x)$.

and suppose $y_1(x)$ solves the homogeneous

equation $y'' + a_1(x)y' + a_2(x)y = 0$.

We know general solution

$$y(x) = \underbrace{y_c}_{C_1 y_1 + C_2 y_2} + y_p \quad \text{we need } y_c \text{ and } y_p$$

Ansatz: $y(x) = u(x) \cdot y_1(x)$ is a solution to

(*)

Start to compute: $y' = u' y_1 + u y_1'$.

$$y'' = u'' y_1 + 2u' y_1' + u y_1''$$

Substitute y into (*)

$$u'' y_1 + 2u' y_1' + \underline{u y_1''} + \underline{a_1(x)} (u' y_1 + \underline{u y_1'}) + \underline{a_2(x) u y_1} = f(x)$$

$$u (\underbrace{y_1'' + a_1(x) y_1' + a_2(x) y_1}_{=0}) + u'' y_1 + 2u' y_1' + a_1(x) u y_1 = f(x)$$

$$u'' y_1 + u' (2y_1' + a_1(x) y_1) = f(x)$$

$$(u')' y_1 + u' (2y_1' + a_1(x) y_1) = f(x)$$

Note: This is a 1st order ODE for u' .

Call $w = u'$.

$$w' y_1 + w (2y_1' + a_1(x) y_1) = f(x)$$

$$w' + w \cdot \left(\frac{2y_1'}{y_1} + a_1(x) \right) = \frac{F(x)}{y_1}$$

Integration factor. $e^{\int^x \left(\frac{2y_1'(s)}{y_1(s)} + a_1(s) \right) ds}$. (multiply on both sides)

$$\left(w \cdot e^{\int^x \left(\frac{2y_1'(s)}{y_1(s)} + a_1(s) \right) ds} \right)' =$$

$$\frac{F(x)}{y_1} \cdot e^{\int^x \left(\frac{2y_1'(s)}{y_1(s)} + a_1(s) \right) ds}$$

Notation $I(x) = e^{\int^x \frac{2y_1'(s)}{y_1(s)} + a_1(s) ds}$.

$$\frac{d}{dx} (w \cdot I) = \frac{F(x)}{y_1(x)} \cdot I(x)$$

$$w(x) = \frac{1}{I(x)} \left(\int^x \frac{I(s) F(s)}{y_1(s)} ds + C_1 \right)$$

$$u'(x) = w \Rightarrow$$

$$u(x) = \int^x \left(\frac{1}{I(t)} \int^t \frac{I(s) F(s)}{y_1(s)} ds \right) dt + C_1 \int^x \frac{1}{I(s)} ds$$

$$+ \underline{C_2}.$$

general solution

$$y(x) = u(x) \cdot y_1(x)$$

$$= \underline{C_2 y_1(x) + C_1 \int^x \frac{1}{I(s)} ds}$$

$$+ \underline{\int_0^x \left(\frac{1}{I(t)} \int^t \frac{I(s)F(s)}{y_1(s)} ds \right) dt}.$$

solution to homogenous equation.
 $y_c(x)$

Use $F(x) = 0$ to find $y_c(x)$

$y_p(x)$

Do Not memorize the preceding formula

Just use the idea $y(x) = u(x) y_1(x)$

and start computing.

Ex: Find the general solution to

$$xy'' - 2y' + (2-x)y = 0 \quad (x > 0)$$

given one solution $y_1(x) = e^x$.

Look for $y(x) = u(x) \cdot e^x$

$$y' = u' \cdot e^x + u e^x$$

$$y'' = \underline{u'' e^x + 2u' e^x + u e^x}$$

$$x \cdot (u'' e^x + 2u' e^x + u e^x) - 2(u' e^x + u e^x) + (2-x) \cdot u \cdot e^x = 0$$

$$\Rightarrow x \cdot u'' + 2u'(x-1) = 0.$$

$$w = u', \quad x \cdot w' + 2w(x-1) = 0.$$

$$w' + \frac{2(x-1)}{x} w = 0.$$

$$\begin{aligned} \text{Integration factor } I(x) &= e^{2 \int 1 - \frac{1}{x}} = e^{2(x - \log x)} \\ &= e^{2x} \cdot e^{-2 \log x} \\ &= \frac{1}{x^2} \cdot e^{2x} \end{aligned}$$

$$\left(w \cdot \frac{1}{x^2} e^{2x} \right)' = 0.$$

$$w = C_1 \cdot x^2 e^{-2x} = u'.$$

$$u(x) = C_1 \int x^2 e^{-2x} dx + C_2$$

$$y(x) = e^x \cdot \left(-\frac{1}{4} C_1 \cdot (1 + 2x + 2x^2) \cdot e^{-2x} + C_2 \right)$$

$$y(x) = C_1 e^{-x} (1 + 2x + 2x^2) + C_2 e^x$$