

$SU(2)$ and orthogonal repn

$$U(2) = \left\{ A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in M_2(\mathbb{C}) \mid \bar{A}^T \cdot A = I \right\}$$

$$SU(2) = \left\{ A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in M_2(\mathbb{C}) \mid \bar{A}^T \cdot A = I, \det A = 1 \right\}$$

$$A^{-1} = \begin{pmatrix} d & -b \\ -c & a \end{pmatrix} = \bar{A}^T$$

$$\Rightarrow a = \bar{d}, \quad b + \bar{c} = 0$$

$$A = \begin{bmatrix} a & b \\ -\bar{c} & \bar{d} \end{bmatrix}, \quad \bar{a}a + \bar{b}\bar{b} = 1$$

$$a = x + y\sqrt{-1}, \quad b = z + w\sqrt{-1}$$

$$|a|^2 + |b|^2 = x^2 + y^2 + z^2 + w^2 = 1.$$

Goal: $SU(2) \xrightarrow{?} SO(3)$



Real repn. and group homs.

$A \in SU(2)$, consider

$$W = \left\{ B \in M_2(\mathbb{C}), \text{ s.t. } \operatorname{tr} B = 0, \underbrace{B^T + \bar{B}}_{\downarrow} = 0 \right\}$$

Then $ABA^{-1} \in W$. $\dim_{\mathbb{R}} = 3$

$$\operatorname{Tr}(ABA^{-1}) = \operatorname{Tr}(B)$$

$$(ABA^{-1})^T = (A B \bar{A}^T)^T = \bar{A} B^T \bar{A}^T = -\bar{A} \bar{B} \bar{A}^{-1}$$

$SU(2) \hookrightarrow W$ and \mathbb{R} -linear

$$\Rightarrow SU(2) \rightarrow GL(3, \mathbb{R})$$

W has an inner product.

$$\langle B, B' \rangle = -\frac{1}{2} \operatorname{Tr}(B B')$$

W has basis

$$\beta_1 = \begin{bmatrix} \sqrt{-1} \\ -\sqrt{-1} \end{bmatrix}, \quad \beta_2 = \begin{bmatrix} i \\ -1 \end{bmatrix}, \quad \beta_3 = \begin{bmatrix} 1 \\ \sqrt{-1} \end{bmatrix}$$

$$\beta_1^2 = -2, \quad \beta_2^2 = -1, \quad \beta_3^2 = -1$$

$$\beta_1 \beta_2 = \begin{pmatrix} 0 & \sqrt{-1} \\ \sqrt{-1} & 0 \end{pmatrix} = \beta_3$$

$$\beta_2 \beta_3 = \beta_1, \quad \beta_3 \beta_1 = \beta_2$$

\langle , \rangle positive definite

$\beta_1, \beta_2, \beta_3$ orthonormal basis

$\rho: SU(2) \rightarrow O(3)$

connected so $Im \rho \subset SO(3)$

Prop: $\ker \rho = \{I\}$ and $\text{Im } \rho = \{D(B)\}$

Pf: $\pm I \subset \ker \rho$

$$AB_i A^{-1} = B_i \Rightarrow \underbrace{A B_i}_{i=1,2,3} = \underbrace{B_i A}_{i=1,2,3}$$

$$i=1,2,3, B_i \Rightarrow A \begin{pmatrix} 1 & \\ & -1 \end{pmatrix} = \begin{pmatrix} 1 & \\ & -1 \end{pmatrix} A$$

$$\begin{pmatrix} a & b \\ -\bar{b} & \bar{a} \end{pmatrix} \begin{pmatrix} 1 & \\ & -1 \end{pmatrix} = \begin{pmatrix} 1 & \\ & -1 \end{pmatrix} \begin{pmatrix} a & b \\ -\bar{b} & \bar{a} \end{pmatrix}$$

$$\begin{pmatrix} a & -b \\ -\bar{b} & -\bar{a} \end{pmatrix} = \begin{pmatrix} a & b \\ \bar{b} & -\bar{a} \end{pmatrix} \Rightarrow b = 0$$

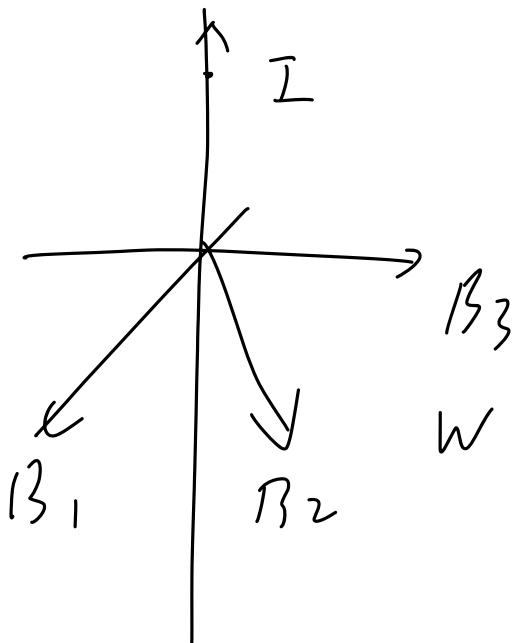
$B_2 \Rightarrow$

$$\begin{pmatrix} a & 0 \\ 0 & \bar{a} \end{pmatrix} \begin{pmatrix} 1 & \\ & -1 \end{pmatrix} = \begin{pmatrix} 1 & \\ & -1 \end{pmatrix} \begin{pmatrix} a & 0 \\ 0 & \bar{a} \end{pmatrix}$$

$$\begin{pmatrix} -\bar{a} & a \\ -a & \bar{a} \end{pmatrix} = \begin{pmatrix} a & 0 \\ -a & \bar{a} \end{pmatrix} \Rightarrow a = \bar{a}$$

$$|a|^2 = 1 \Rightarrow a = \pm 1.$$

$\text{Im } \rho:$ rotation



Claim:

$$SU(2) \hookrightarrow W$$

action transitive

$$\text{on } S^2 \subset W$$

$$\left\{ a_1\beta_1 + a_2\beta_2 + a_3\beta_3 \mid \sum a_i^2 = 1 \right\}$$

$$C = \left\{ B \in SU(2) \mid \overline{\text{Tr}} B = 0 \right\}$$

eigenvalues of $A \in SU(2)$ are

$$\lambda, \bar{\lambda}, \quad \lambda \cdot \bar{\lambda} = 1,$$

$$\text{Tr } A = \lambda + \bar{\lambda},$$

If $\lambda, \bar{\lambda}$ are distinct.

then eigen vectors v_1, v_2 are orthogonal, rescale to orthonormal

$$\Rightarrow \underbrace{A(v_1, v_2)}_{P} = (v_1, v_2) \begin{pmatrix} \lambda & \\ & \bar{\lambda} \end{pmatrix}$$

rescale P to $\det P = 1$

$$\Rightarrow P \in SU(2), PAP^{-1} = \begin{pmatrix} \lambda & \\ & \bar{\lambda} \end{pmatrix}$$

Applying to $B \in SU(2)$, $\text{tr } B = 0$

$$\Rightarrow PBP^{-1} = \begin{pmatrix} \sqrt{\lambda} & \\ & -\sqrt{\lambda} \end{pmatrix} = B_1$$

Stab _{B_1} in $SU(2)$ is $\begin{pmatrix} a & 0 \\ 0 & \bar{a} \end{pmatrix}$

and $a = e^{\sqrt{\lambda}\theta}$, then A_θ

$$\begin{aligned} A_\theta &= \cos \theta \cdot \begin{pmatrix} 1 & \\ & 1 \end{pmatrix} + \sin \theta \begin{pmatrix} \sqrt{\lambda} & \\ & -\sqrt{\lambda} \end{pmatrix} \\ &= \cos \theta I + \sin \theta B_1 \end{aligned}$$

$$A_\theta^{-1} = \cos \theta I - \sin \theta B_1$$

$$A_\theta B_2 A_\theta^{-1} = (\cos \theta + \sin \theta B_1) \cdot B_2$$

$$(\cos \theta - \sin \theta B_1)$$

$$= (\cos^2 \theta - \sin^2 \theta) B_2 + 2 \sin \theta \cos \theta B_3$$

$$A_\theta B_3 A_\theta^{-1} = (-2 \sin \theta \cos \theta) B_2$$

$$+ (\cos^2 \theta - \sin^2 \theta) B_3$$

$$P(A_\theta) \cdot (B_1, B_2) = (B_1, B_2) \cdot \begin{pmatrix} \cos 2\theta & -\sin 2\theta \\ \sin 2\theta & \cos 2\theta \end{pmatrix}$$

↙
rotation by 2θ

Then $P A_\theta P^{-1}$ can realize all rotations by any angle.

$$\text{Im } P = \text{SO}(3)$$

D.

Now any finite subgroup $\overset{G}{\sim}$ of $SU(2)$ has the following description

$$\rho: SU(2) \rightarrow SO(3)$$

$$\rho|_G: G \longrightarrow SO(3)$$

$$\rho: G \xrightarrow{2:1} I_m G \quad \text{or} \quad \rho: G \xrightarrow{1:1} I_m G$$

Classification and rep'n's.